### **CTE Series**

# THYRA Drives & Control Systems

#### High Quality

The hardware design and components selection are more optimized and reasonable;

#### High Power Density

♦ The structure design layout is more compact;

#### High Performance

The software upgrade is more compatible with the end user, industrial control is more flexible, accurate, and the performance is stronger, and it is more suitable for precision control occasions with higher requirements for torque, control accuracy, and response speed;

#### Optimize Products User Experience

Easy operation, maintainability, environmental protection, scalability and convenience of Int-ernet of Things access.

CT10M:Power Rate

1 phase & 3 phase Input 3 phase output

220V (+-20%) 0.4KW~4.0KW

380V (+-20%) 0.4KW~400KW





# ♦ SI

## **SPECIFICATION**

#### Input & Output

1AC 220~240V(± 15%)
3AC 220~240V(± 15%)
3AC 380~460V(± 15%)
50Hz/60Hz ±5%
0~input voltage, deviation <±3%
0~600Hz

#### **Control Characteristics**

Control mode	v/f control Sensor-less vector control Torque control
Speed accuracy	±0,5% (V/f) ±0,2% (SVC)
Speed fluctuation	±0,3% (SVC)
torque response	< 10ms (SVC)
Starting torque	0,5Hz: 150% (V/f) 0,25Hz: 180% (SVC)
Overload capability	150% Rated current -60s 180% Rated current -10s 200% Rated current -1s
Simple PLC Multi-step speed	16 speed External digital signal control Internal clock
PID function	Standard build-in
Communication	Modbus

#### Featured functions

Input &Output delay
Flexible parameters display
AVR (Automatic Voltage Regulation)
Timing control, fixed length control, etc.
Simple PLC, 16-steps speed control
Torque control build-in
S curve acceleratior/deceleration Multi-functional programmable keypad V/f separated control

#### **Environment Limitation**

Installation location	Without direct sunlight, free from dust, corrosive gases, oil mist, flammable gases, water vapor, water drop and salt, etc.
Altitude	0~2000m Derated 1% for every 1000m when the altitude is above 1000meters
Ambient temperature	-10°C~50°C (Output derated while the temperature is higher than 40°C)
Storage temperature	-20°C~+70°C
Relative Humidity	5-95% no condensation

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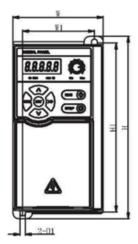


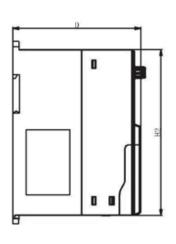
#### Protection

Overcurrent、Overvoltage、PID feedback failure、Overheat、Undervoltage、The main contactor is abnormal、Motor overload、Fast protection、Unbalanced output、Frequency conversion overload、System abnormal、Motor detection abnormalOutput phase loss、Input phase loss、Short circuit protection of control board power supply.



## **TECHNICAL SPECIFICAT**





Model	Outer Dimensions (mm)				Fixing	weight		
iviodei	W1	H1	Н	H2	W	D	hole	(kg)
CTE-2S-0. 4B								
CTE-28-0. 75B								
CTE-2S-1.5B								
CTE-2S-2. 2B	67.5	160	170	/	84.5	129	ø4.5	1.0
CTE-4T-0. 75B								
CTE-4T-1.5B								
CTE-4T-2. 2B								
CTE-2S-2. 0B	- 85							
CTE-2S-4. 0B		185	194	,	97	143.5	ø5.5	1.4
CTE-4T-4.0B		103	154	<b>'</b>	, , , , , , , , , , , , , , , , , , ,	140.5	0.5	1.4
CTE-4T-5. 5B	]							

Category	Terminal symbol	Terminal name	Function Description
Power supply	+10V-GND	External +10V power	Provides +10V power to the outside, maximum output current: 10mA Used as a working power supply for external potentiometer, resistance range: $1 k \Omega^{-5} 0 k \Omega$
Analog input	AI1-GND	Analog input terminal 1	Input voltage: DC 0V~10V/4mA~20mA, input impedance 100K.
Digital input	Xi- GND	Digital input I	<ol> <li>Optical coupling isolation, compatible with bipolar input</li> <li>Input impedance: 4.7kΩ</li> <li>Voltage range for level input: 9V~30V</li> </ol>
Analog output	AO1-GND	Analog output	The voltage or current output is determined by the AO1 jumper selection on the control board. Output voltage range: OV~10V, output current range: OmA~20mA
Digital output	Y/DO-GND	Digital output (compatible with high- speed output out)	Optocoupled isolation, bipolar open collector output Output voltage range: OV~24V, output current range: OmA~50Ma
Relay	RA-RB	RA-RB Normally closed terminal Contact actuation capability:	
output	RA-RC	Always open	AC250V, 3A; DC 30V, 3A。